

# Appendix A

## Extinction and reddening

### A.1 Extinction and reddening for NGC 6204 and Hogg 22

#### NGC 6204

$$(B - V) - (B_0) - (V_0) = 0.430 \text{ (Obtained from WEBDA)}$$

$$\therefore (B - B_0) - (V - V_0) = 0.430$$

but  $(B - B_0) = A_b$  and  $(V - V_0) = A_v$  (Extinction in B and V respectively)

$$\therefore A_b - A_v = 0.430 \text{ (Reddening)}$$

but  $A_b/A_v = 1.324$  (From (Rieke & Lebofsky, 1985))

$$\therefore 1.324A_v - A_v = 0.324A_v = 0.430$$

$$\therefore A_v = 0.430/0.324$$

$$\therefore A_v = 1.32$$

#### Hogg 22

$$(B - V) - (B_0) - (V_0) = 0.647 \text{ (Obtained from WEBDA)}$$

$$\therefore (B - B_0) - (V - V_0) = 0.647$$

but  $(B - B_0) = A_b$  and  $(V - V_0) = A_v$  (Extinction in B and V respectively)

$$\therefore A_b - A_v = 0.647 \text{ (Reddening)}$$

but  $A_b/A_v = 1.324$  (From (Rieke & Lebofsky, 1985))

$$\therefore 1.324A_v - A_v = 0.324A_v = 0.647$$

$$\therefore A_v = 0.647/0.324$$

$$\therefore A_v = 1.99$$

# Appendix B

## Computer code

The following part of the computer code is responsible for calculating image rotation and translation after which the coordinate transformation from image coordinates to the master list coordinates is done.

```
#include <string.h>
#include <stdio.h>
#include <stdlib.h>
#include <math.h>

int main(int argc, char **argv)
{
    if (argc != 2)
    {
        printf("usage: %s filename \n", argv[0]);
    }

    //////////////////////////////////////
    FILE *fp1;                               /*variables*/
    FILE *fp2;
    FILE *fp3;
    FILE *fp4;
    FILE *fp5;
    FILE *fp6;
    FILE *fp7;
    FILE *fp8;

    float  b1[5000], b2[5000], b3[5000], b4[5000], b5[5000], b6[5000], b7[5000];
    float  v1[5000], v2[5000], v3[5000], v4[5000], v5[5000], v6[5000], v7[5000];
    float  i1[5000], i2[5000], i3[5000], i4[5000], i5[5000], i6[5000], i7[5000];
    float  ximage[20000], yimage[20000], alphaRad[5000], alphaDeg[500], pixdistA[500],
          pixdistB[500], coords[46][6], coordsA[1000][6], coordsB[1000][6];
    float  a1[200], a2[200], a3[200], a4[200], a5[200], a6[200], x1[200], x2[200],
          x3[200], c1[200], c2[200], c3[200], e1[200], e2[200], e3[200];
```

```
float d1, d2, d3, d4, d5, d6, d7, x0, y0, t[200], t1[200], t2[200], f1, f2, f3,
      f4, f5, f6;
int i,j,k,l,y,g,q, nlines1, nlines2, nlines3;

//#####

if((fp1=fopen("master.fit.coo.1", "r")) == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}

if((fp2=fopen(argv[1], "r")) == NULL) {
    printf("Cannot open file.\n", argv[1]);
    exit(1);
}

if((fp3=fopen("masterbright.coords", "w+") == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}

if((fp4=fopen("image.coords", "w+") == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}

if((fp5=fopen("out1", "w+") == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}

if((fp6=fopen("out2", "w+") == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}

if((fp7=fopen("out.coords", "w+") == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}

if((fp8=fopen("master.coords", "r")) == NULL) {
    printf("Cannot open file.\n");
    exit(1);
}
```

```

#####
char line[256], *tmpchar;                                /*read number of lines*/
nlines1 = 0;
while (fgets(line, sizeof(line), fp1) != NULL)
{
    tmpchar = &line[0];
    while((!feof(fp1)) && (*tmpchar == ' ') && (*tmpchar != '\0'))
    {
        tmpchar++;
        fscanf (fp1, "%f%f%f%f%f%f", &d1, &d2, &d3, &d4, &d5, &d6, &d7);
        nlines1 = nlines1 + 1;
    }
}
nlines1 = nlines1 - 1;
printf("%d \n", nlines1);

nlines2 = 0;
while (fgets(line, sizeof(line), fp2) != NULL)
{
    tmpchar = &line[0];
    while((!feof(fp2)) && (*tmpchar == ' ') && (*tmpchar != '\0'))
    {
        tmpchar++;
        fscanf (fp2, "%f%f%f%f%f%f", &d1, &d2, &d3, &d4, &d5, &d6, &d7);
        nlines2 = nlines2 + 1;
    }
}
nlines2 = nlines2 - 1;
printf("%d \n", nlines2);

nlines3 = 0;
while (fgets(line, sizeof(line), fp8) != NULL)
{
    tmpchar = &line[0];
    while((!feof(fp8)))
    {
        tmpchar++;
        fscanf (fp8, "%f%f", &d1, &d2);
        nlines3 = nlines3 + 1;
    }
}

#####
rewind(fp1);                                           /*read from iraf coords file*/
rewind(fp2);

i=1;

```

```

while (fgets(line, sizeof(line), fp1) != NULL)
{
    tmpchar = &line[0];
while (((*tmpchar == ' ') && (*tmpchar != '\0'))
    tmpchar++;
    i++;
    if ((*tmpchar == '#') || (*tmpchar == '\0') || (*tmpchar == '\n'))
        continue;
    sscanf(tmpchar, "%f %f", &b1[i], &b2[i]);
    // fprintf(stdout, "%f \n" ,b1[i]);
    // fprintf(stdout, "%f \t %f \n", b1[i], b2[i]);
    fprintf(fp3, "%f \t %f \n",b1[i], b2[i]);
}

j=1;
while (fgets(line, sizeof(line), fp2) != NULL)
{
    tmpchar = &line[0];
while (((*tmpchar == ' ') && (*tmpchar != '\0'))
    tmpchar++;
    j++;
    if ((*tmpchar == '#') || (*tmpchar == '\0') || (*tmpchar == '\n'))
        continue;
    sscanf(tmpchar, "%f %f", &b3[j], &b4[j]);
    // fprintf(stdout, "%f \n" ,b1[i]);
    // fprintf(stdout, "%f \t %f \n", b1[i], b2[i]);
    fprintf(fp4, "%f \t %f \n", b3[j], b4[j]);
}

//#####
rewind(fp3);          /*read from output coords files into v and i*/
rewind(fp4);

for(i=0;i<nlines1;i++){
    fscanf(fp3, "%f \t %f \n", &v1[i], &v2[i]);    // Scan masterbright.coords
}

for(i=0;i<nlines2;i++){
    fscanf(fp4, "%f \t %f \n", &i1[i], &i2[i]);        // Scan image.coords
}

//#####
for(i=0;i<nlines1;i++){    /*cross identify stars in two images with distances*/
    for(j=i+1;j<nlines1-1;j++){

/*distances between two stars in first frame*/
        pixdistA[i]=sqrt(pow((v1[i]-v1[j]),2)+pow((v2[i]-v2[j]),2));

```

```

        fprintf(fp5, "%i %f %f %f %f %f \n", i, v1[i],v2[i],v1[j],v2[j], pixdistA[i]);
//    fprintf(stdout, "%i %f %f %f %f %f \t %f %f %f %f %f \n", i, v1[i],v2[i],
//        v1[j],v2[j], pixdistA[i], i1[i], i2[i], i1[j], i2[j], pixdistB[i]);

    }
}
printf("\n");

for(i=0;i<nlines2;i++){
    for(j=i+1;j<nlines2-1;j++){

/*distances between two stars in second frame*/
        pixdistB[i]=sqrt(pow((i1[i]-i1[j]),2)+pow((i2[i]-i2[j]),2));
        fprintf(fp6, "%i %f %f %f %f %f \n", i, i1[i],i2[i],i1[j],i2[j], pixdistB[i]);

    }
}
printf("\n");

rewind(fp5);
rewind(fp6);

for (i=0;i<100;i++)
{

fscanf(fp5, "%f %f %f %f %f %f \n", &coordsA[i][0], &coordsA[i][1], &coordsA[i][2],
&coordsA[i][3], &coordsA[i][4], &coordsA[i][5]);

}

/*Print unsorted arrays*/

/*for (k=0;k<nlines1-1;k++)
{
    for (l=0;l<6;l++)
    {
        printf("%8f ", coordsA[k][l]);
    }
    printf("\n");
}
printf("\n\n");
*/

for (i=0;i<100;i++)
{

fscanf(fp6, "%f %f %f %f %f %f \n", &coordsB[i][0], &coordsB[i][1], &coordsB[i][2],
&coordsB[i][3], &coordsB[i][4], &coordsB[i][5]);

```

```

    }
/*   for (k=0;k<nlines2-1;k++)
    {
    for (l=0;l<6;l++)
    {
    printf("%8f ", coordsB[k][l]);
    }
    printf("\n");
    }
printf("\n\n");
*/

//##### Initialize coords arrays #####

for(i=0;i<900;i++)                /*Sort coordinate arrays by pixel distances*/
{
    for(j=0; j<900-1-i; j++)
    {
        if(coordsA[j+1][5] > coordsA[j][5])
        {
            f1 = coordsA[j][5];
            coordsA[j][5] = coordsA[j+1][5];
            coordsA[j+1][5] = f1;
            f2 = coordsA[j][4];
            coordsA[j][4] = coordsA[j+1][4];
            coordsA[j+1][4] = f2;
            f3 = coordsA[j][3];
            coordsA[j][3] = coordsA[j+1][3];
            coordsA[j+1][3] = f3;
            f4 = coordsA[j][2];
            coordsA[j][2] = coordsA[j+1][2];
            coordsA[j+1][2] = f4;
            f5 = coordsA[j][1];
            coordsA[j][1] = coordsA[j+1][1];
            coordsA[j+1][1] = f5;
            f6 = coordsA[j][0];
            coordsA[j][0] = coordsA[j+1][0];
            coordsA[j+1][0] = f6;
        }
    }
}

for(i=0;i<900-1;i++)
{
    for(j=0; j<900-1-i; j++)
    {
        if(coordsB[j+1][5] > coordsB[j][5])
        {

```

```

        f1 = coordsB[j][5];
        coordsB[j][5] = coordsB[j+1][5];
        coordsB[j+1][5] = f1;
        f2 = coordsB[j][4];
        coordsB[j][4] = coordsB[j+1][4];
        coordsB[j+1][4] = f2;
        f3 = coordsB[j][3];
        coordsB[j][3] = coordsB[j+1][3];
        coordsB[j+1][3] = f3;
        f4 = coordsB[j][2];
        coordsB[j][2] = coordsB[j+1][2];
        coordsB[j+1][2] = f4;
        f5 = coordsB[j][1];
        coordsB[j][1] = coordsB[j+1][1];
        coordsB[j+1][1] = f5;
        f6 = coordsB[j][0];
        coordsB[j][0] = coordsB[j+1][0];
        coordsB[j+1][0] = f6;
    }
}

/*Print coordinate arrays */
for (k=0;k<100;k++)
{
    for(l=0;l<6;l++)
    {
        printf("%8f ", coordsA[k][l]);
    }
    printf("\n");
}

printf("\n\n");

for (k=0;k<100;k++)
{
    for(l=0;l<6;l++)
    {
        printf("%8f ", coordsB[k][l]);
    }
    printf("\n");
}

printf("\n\n");

for(i=0;i<800;i++){          /*Assign new sorted values to coordsA & coordsB arrays */
for(j=0;j<800;j++){
    v1[i+i]=coordsA[i][1];

```

```

v2[i+i]=coordsA[i][2];
v1[2*j+1]=coordsA[j][3];
v2[2*j+1]=coordsA[j][4];
}
}

for(i=0;i<800;i++){
for(j=0;j<800;j++){
i1[i+i]=coordsB[i][1];
i2[i+i]=coordsB[i][2];
i1[2*j+1]=coordsB[j][3];
i2[2*j+1]=coordsB[j][4];
}
}

printf("\n");
printf("\n\n");

for(g=0;g<800;g++){
for(i=0;i<900;i++){
//fprintf(stdout, "%i \n", g);
if ((coordsB[i][5] > coordsA[g][5] - 2.0)&&(coordsB[i][5] < coordsA[g][5] + 2.0)){
if (((coordsA[g+1][5]<coordsA[g][5]-3)&&(coordsA[g-1][5]>coordsA[g][5]+3))&&
((coordsB[i+1][5]<coordsB[i][5]-3)&&(coordsB[i-1][5]>coordsB[i][5]+3))){

fprintf(stdout, "%f \n", coordsA[g][5]);
printf("\n\n");
fprintf(stdout, "%f \n", coordsB[i][5]);
q=5;

v1[0]=coordsA[g][1];
v2[0]=coordsA[g][2];
v1[1]=coordsA[g][3];
v2[1]=coordsA[g][4];
i1[0]=coordsB[i][1];
i2[0]=coordsB[i][2];
i1[1]=coordsB[i][3];
i2[1]=coordsB[i][4];
break;
}
}
else {
//printf("not found \n");
continue;
}
}
if (q==5)

```

```

break;
}

printf("\n\n");
printf("\n\n");

//#####

a1[0]=v1[0]-v1[1];          /*a1-a6 : simplify x0 y0 elliminated equation*/
a2[0]=i1[0]+(-1)*i1[1];
a3[0]=(-1)*i2[0]+i2[1];
a4[0]=v2[0]-v2[1];
a5[0]=i1[0]+(-1)*i1[1];
a6[0]=i2[0]+(-1)*i2[1];

x1[0]=a1[0]+a4[0];
x2[0]=a2[0]+a6[0];
x3[0]=a5[0]+a3[0];

c1[0]=x1[0]/x1[0];
c2[0]=x2[0]/x1[0];
c3[0]=x3[0]/x1[0];

e1[0]=c1[0]+c2[0];
e2[0]=(-1)*2*c3[0];
e3[0]=c1[0]-c2[0];

t1[0]=(((-1)*e2[0])-sqrtf((e2[0]*e2[0])-(4*e1[0]*e3[0])))/(2*e1[0]);
t2[0]=(((-1)*e2[0])+sqrtf((e2[0]*e2[0])-(4*e1[0]*e3[0])))/(2*e1[0]);

/*Choose between two roots of quadratic equation*/
if ( fabsf(0 - t1[0]) < fabsf(0 - t2[0]) )
    t[0] = t1[0];
    else
    {
        t[0] = t2[0];
    }

    alphaRad[0] = atan(t[0])*2;
    alphaDeg[0] = alphaRad[0] * (180/3.141592654);

fprintf(stdout, "%f %f %f %f %f %f %f %f \t %f \t %f %f %f \n", v1[0], v2[0],
    v1[1], v2[1], i1[0], i2[0], i1[1], i2[1], t[0], t1[0],t2[0], alphaDeg[0]);

```

```
/*Translation in x and y direction*/
x0=v1[1]+i2[1]*sin(alphaRad[0])-i1[1]*cos(alphaRad[0]);
y0=v2[1]-i2[1]*cos(alphaRad[0])-i1[1]*sin(alphaRad[0]);

printf("\n\n");

    fprintf(stdout, "%f %f %f \n", x0, y0, alphaDeg[0]);

rewind(fp7);                /*read from output coords files into b1 & b2*/
rewind(fp8);

    for(i=0;i<nlines3;i++){
        fscanf(fp8, "%f \t %f \n", &b1[i], &b2[i]);

/*Transformation from master to image coordinates*/
        ximage[i]=(b1[i]-x0)*cos(alphaRad[0])+(b2[i]-y0)*sin(alphaRad[0]);
        yimage[i]=(b2[i]-y0)*cos(alphaRad[0])-(b1[i]-x0)*sin(alphaRad[0]);

        fprintf(fp7, "%f %f \n", ximage[i], yimage[i]);

    }
    printf("%d \n", nlines3);

fclose(fp1);
fclose(fp2);
fclose(fp3);
fclose(fp4);
fclose(fp5);
fclose(fp6);
fclose(fp7);
return 0;
}
```

The following part of the computer code is the IRAF photometry script, calling the above coordinate transformation code and doing both PSF photometry and aperture photometry.

```

procedure autophot(iraflist)
string iraflist {"list",prompt="list of images to reduce"}
string simages {"list.allnn",prompt="list of images in which PSFs found"}
real scale {1.0,prompt="Image scale in units per pixel"}
real fwhm {3.5,min=1,max=8,prompt="full width at half maximum"}
real threshold {4.0,min=1,prompt="threshold in sigma for feature detection"}
real thresh2 {6.0,min=1,prompt="second iteration threshold in sigma for feature detection"}
real nsigma {15.,min=1,prompt="number of sigma below mean for datamin"}
real datamax {45000.,prompt="Maximum good data value"}
real aperture {4.,prompt="aperture radius in scale units"}
real sannulus {10.,prompt="inner radius of sky annulus in scale units"}
real wannulus {10.,prompt="width of sky annulus in scale units"}
string salgo {"mode",prompt="Sky fitting algorithm"}
real psfrad {14.,min=1,prompt="radius of psf in scale units"}
real nspsfrad {11.,min=1,prompt="radius of psf for nstar in scale units"}
real fitrad {4.,prompt="fit radius in scale units"}
int psfiter {2,min=1,max=2,prompt="number of PSF iterations (1 | 2)"}
int allsiter {2,min=1,max=2,prompt="number of allstar iterations (1 | 2)"}
real gain {0.75,prompt="gain of CCD in electrons per counts"}
real readnoise {6.5,prompt="CCD readout noise in electrons"}
int maxnpsf {20,min=1,prompt="Maximum number of PSF star to select automatically"}
int nclean {2,prompt="Number of cleaning iterations for computing psf"}
real mergerad {INDEF,prompt="Critical object merging radius in scale units"}
string errlog {"bug_log",prompt="log of problems file"}
string exposurek {"exptime",prompt="Exposure time header keyword"}
string airmassk {"airmass",prompt="Airmass header keyword"}
string filterk {"filters",prompt="Filter header keyword"}
string timek {"ut",prompt="Time of observation header keyword"}
string datek {"date-obs",prompt="Date of observation header keyword"}
bool del_sub {no,prompt="Delete *.sub.# images after reduction"}
bool im_disp {no,prompt="Display subtracted image after processing"}
struct *lis
struct *lis1
struct *pstlis
begin
real sky_noise # sky noise
real sky # sky level
real datamin # minimum good value to use
real zmag
string imname
real im_sigma # image standard deviation
string pst_line # line from pst file
string coords # name of stars plate coordinates file
string head # file with Gaussian parameters
string pst_st

```

```

string  str_psfiter      # string of psf number of iteration
int     npst             # number+65 of PSF stars found by pstselect
string  last_psf        # psf image name
zmag = 25.0
delete (simages,verify=no,>>&"/dev/null")
lis=iraflist
head="tmp.header"
while (fscan (lis, imname) != EOF)
{
  coords = imname // '.coo.1'
  delete ('tmp_trsh',verify=no,>>&"/dev/null")
  # find threshold in ADU
  findthresh (images=imname, gain=gain, readnoi=readnoise, ,coaddtype="average",
              nframes=1, center="mode", verbose=no) | scan(sky_noise, im_sigma)
  sky = ((gain*sky_noise)**2) - (readnoise**2)/gain # calculate sky value
  datamin = sky - nsigma*sky_noise

  #-----
  # DAOFIND - Find stars in image
  #-----
  print (' Find stars using Daofind')
  delete (imname//'.coo.*',verify=no,>>&"/dev/null")
  daofind(image=imname, output="default", verify=no, verbose=yes, thresho=threshold,
          scale=scale, fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin, datamax=datamax,
          noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposureek, airmass=airmassk,
          filter=filterk, obstime=timek)
  psort (imname // ".coo.1","MAG",ascend=yes)
  print ("!coordtransform " // imname // ".coo.1") | cl()
  mv ("out.coords",  imname // ".coo.1")

  #-----
  # PHOT - aperture photometry for stars in the image
  #       used as initial guess for DAOPHOT
  #-----
  phot: #   doing the aperture photometry
  print (' Doing the aperture photometry for image : ',imname)
  delete (imname//'.mag.*',verify=no,>>&"/dev/null")
  phot (image=imname, coords="default", output=imname//'.mag.0', interac=no, verify=no,
        verbose=yes, scale=scale, fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin,
        datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposureek,
        airmass=airmassk, filter=filterk, obstime=timek, weighti="constant", apertur=aperture,
        zmag=zmag, salgori=salgo, annulus=sannulus, dannulu=wannulus, calgori="none")

  # Delete pst files
  delete (imname//'.pst.*',verify=no,>>&"/dev/null")

  cp ("pstlist",  imname // ".pst.0")

```

```

imdelete (imname//'.psf.*',verify=no,>>&"/dev/null")
delete (imname//'.psg.*',verify=no,>>&"/dev/null")
delete ('plots',verify=no,>>&"/dev/null")
print(' Calculating the PSF for image : ',imname)
# check if psf list is empty
pst_st = imname // ".pst.0"
count (pst_st) | fields("", "1") | scan(npst)
imdel (imname//'.sub.*',verify=no)
delete (imname//'.nst.*',verify=no,>>&"/dev/null")
delete (imname//'.nrj.*',verify=no,>>&"/dev/null")

if (npst > 66)
{
  psf(image=imname, photfile=imname//'.mag.0', pstfile=imname //'.pst.0',
      psfimage=imname//'.psf.0', opstfile=imname //'.pst.1', groupfil=imname//'.grp.0',
      interac=no, verify=no, scale=scale, fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin,
      datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposurek,
      airmass=airmassk, filter=filterk, obstime=timek, functio="gauss",
      varorde=2, saturat=no, psfrad=psfrad, fitrad=fitrad, recente=yes, fitsky=yes,
      sannulu=sannulus, wsannul=wannulus, nclean=nclean)

  # number of PSF iterations
  if (psfiter==1)
  {
    # one PSF iteration, allready done
  }
  else
  {

# doing the second PSF iteration
nstar(image=imname, groupfil=imname//'.grp.0',psfimage=imname//'.psf.0',
      nstarfil=imname//'.nst.0', rejfile="default", verify=no, scale=scale, fwhmpsf=fwhm,
      sigma=sky_noise, datamin=datamin, datamax=datamax, noise="poisson",
      readnoi=readnoise, epadu=gain, exposur=exposurek, airmass=airmassk,
      filter=filterk, obstime=timek, functio="gauss", varorde=2, psfrad=nspsfrad,
      fitrad=fitrad, recente=yes, fitsky=yes, sannulu=sannulus, wsannul=wannulus,
      mergerad=mergerad)
#imdel (imname//'.sub.*',verify=no)
substar(image=imname, photfile=imname//'.nst.0', exfile="pstlist", psfimage=imname//'.psf.0',
      subimag=imname//'.sub.0', verify=no, scale=scale, fwhmpsf=fwhm, sigma=sky_noise,
      datamin=datamin, datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain,
      exposur=exposurek, airmass=airmassk, filter=filterk, obstime=timek, functio="gauss",
      varorde=2, psfrad=nspsfrad, fitrad=fitrad, recente=no, fitsky=yes, sannulu=sannulus,
      wsannul=wannulus)
delete (imname//'.sub.1.pst.*',verify=no,>>&"/dev/null")
psf(image=imname//'.sub.0', photfile=imname//'.nst.0', pstfile=imname //'.pst.1',
      psfimage=imname//'.psf.1', opstfile=imname //'.pst.2', groupfil=imname//'.grp.1',
      interac=no, verify=no, scale=scale, fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin,

```

```

datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposurek,
airmass=airmassk, filter=filterk, obstime=timek, functio="gauss", varorde=2, saturat=no,
psfrad=psfrad, fitrad=fitrad, recente=yes, fitsky=yes, sannulu=sannulus, wsannul=wannulus,
nclean=nclean)

# doing the third PSF iteration
nstar(image=imname, groupfil=imname//'.grp.1', psfimage=imname//'.psf.1',
nstarfil=imname//'.nst.1', rejfile="default", verify=no, scale=scale,
fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin, datamax=datamax,
noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposurek,
airmass=airmassk, filter=filterk, obstime=timek, functio="gauss",
varorde=2, psfrad=psfrad, fitrad=fitrad, recente=yes, fitsky=yes,
sannulu=sannulus, wsannul=wannulus, mergerad=mergerad)
#imdel (imname//'.sub.*',verify=no)
substar(image=imname, photfile=imname//'.nst.1', exfile="pstlist",
psfimage=imname//'.psf.1', subimag=imname//'.sub.1', verify=no,
scale=scale, fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin,
datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain,
exposur=exposurek, airmass=airmassk, filter=filterk, obstime=timek,
functio="gauss", varorde=2, psfrad=psfrad, fitrad=fitrad,
recente=no, fitsky=yes, sannulu=sannulus, wsannul=wannulus)
delete (imname//'.sub.2.pst.*',verify=no,>>&"/dev/null")
psf(image=imname//'.sub.1', photfile=imname//'.nst.1', pstfile=imname //'.pst.2',
psfimage=imname//'.psf.2', opstfile=imname //'.pst.3', groupfil=imname//'.grp.2',
interac=no, verify=no, scale=scale, fwhmpsf=fwhm, sigma=sky_noise, datamin=datamin,
datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposurek,
airmass=airmassk, filter=filterk, obstime=timek, functio="gauss", varorde=2, saturat=no,
psfrad=psfrad, fitrad=fitrad, recente=yes, fitsky=yes, sannulu=sannulus, wsannul=wannulus,
nclean=nclean)

#-----
# starting allstar
#-----
allstar1: # fitting the PSF and measuring all the stars
print (' measuring allstars in ',imname)
#imdelete (imname//'.sub.*',verify=no,>>&"/dev/null")
delete (imname//'.als.*',verify=no,>>&"/dev/null")
delete (imname//'.arj.*',verify=no,>>&"/dev/null")
# ----- First Sweep of ALLSTAR -----
last_psf = imname//'.psf.2'
allstar(image=imname, photfile=imname//'.mag.0', psfimage=last_psf,
allstarf=imname//'.als.1", rejfile="default", subimage=imname//'.sub.2",
verbose="yes", verify=no, scale=scale, fwhmpsf=fwhm, sigma=sky_noise,
datamin=datamin, datamax=datamax, noise="poisson", readnoi=readnoise, epadu=gain,
exposur=exposurek, airmass=airmassk, filter=filterk, obstime=timek, functio="gauss",
varorde=2, psfrad=psfrad, fitrad=fitrad, recente=yes, fitsky=yes,
sannulu=sannulus, wsannul=wannulus, mergerad=mergerad)

```

```

# clean the als file from INDEF stars
print(' cleaning '//imname//'.als.1')
delete (imname//'.sfs.*',verify=no,>>&"/dev/null")
txdump(textfile=imname//'.als.1', fields="ID,XCENTER,YCENTER,MAG,MERR,MSKY,
      NITER,SHARPNESS, CHI", expr="MAG[1] !=INDEF", headers=yes, >imname//'.sfs.1')
#-----

hselect (imname//'.psf.2.fits',"PAR1", "PAR1>0", missing="INDEF") | scan(x)
hselect (imname//'.psf.2.fits',"PAR2", "PAR2>0", missing="INDEF") | scan(y)
z =(x + y)

txdump(textfile=imname//'.als.1',fields="XCENTER,YCENTER,MAG,MERR,SHARPNESS,ID",
      expr="ID>0", headers=yes,>imname//'.als.2')

#-----
# PHOT - aperture photometry for stars in the image
#       used as initial guess for allstar 2nd iteration
#-----
print (' Doing the aperture photometry for image : ',imname)
delete (imname//'.sub.*.mag.*',verify=no,>>&"/dev/null")

phot (image=imname, coords=imname //'.als.2', output=imname//'.mag.1',
      interac=no, verify=no, verbose=yes, scale=scale, fwhmpsf=fwhm,
      sigma=sky_noise, datamin=datamin, datamax=datamax,
      noise="poisson", readnoi=readnoise, epadu=gain, exposur=exposurek,
      airmass=airmassk, filter=filterk, obstime=timek, weighti="constant",
      apertur=z, zmag=zmag, salgori=salgo, annulus=sannulus,
      dannulu=wannulus, calgori="none")
txdump(textfile=imname//'.mag.1',fields="ID,XCENTER,YCENTER,MAG,MERR,SHARPNESS",
      expr="ID>0", headers=yes,>imname//'.ape.1')

x=1.5*z

phot (image=imname, coords=imname //'.als.2', output=imname//'.mag.2', interac=no,
      verify=no, verbose=yes, scale=scale, fwhmpsf=fwhm, sigma=sky_noise,
      datamin=datamin, datamax=datamax, noise="poisson", readnoi=readnoise,
      epadu=gain, exposur=exposurek, airmass=airmassk, filter=filterk,
      obstime=timek, weighti="constant", apertur=x, zmag=zmag, salgori=salgo,
      annulus=sannulus, dannulu=wannulus, calgori="none")
txdump(textfile=imname//'.mag.2',fields="ID,XCENTER,YCENTER,MAG,MERR,SHARPNESS",
      expr="ID>0", headers=yes,>imname//'.ape.2')

x=2.0*z

phot (image=imname, coords=imname //'.als.2', output=imname//'.mag.3',
      interac=no, verify=no, verbose=yes, scale=scale, fwhmpsf=fwhm,
      sigma=sky_noise, datamin=datamin, datamax=datamax, noise="poisson",
      readnoi=readnoise, epadu=gain, exposur=exposurek, airmass=airmassk,
      filter=filterk, obstime=timek, weighti="constant", apertur=x, zmag=zmag,
      salgori=salgo, annulus=sannulus, dannulu=wannulus, calgori="none")

```

```

txdump(textfile=imname//'.mag.3',fields="ID,XCENTER,YCENTER,MAG,MERR,
        SHARPNESS", expr="ID>0", headers=yes,>imname//'.ape.3')

x=2.5*z

phot (image=imname, coords=imname //'.als.2', output=imname//'.mag.4',
      interac=no, verify=no, verbose=yes, scale=scale, fwhmpsf=fwhm,
      sigma=sky_noise, datamin=datamin, datamax=datamax, noise="poisson",
      readnoi=readnoise, epadu=gain, exposur=exposurek, airmass=airmassk,
      filter=filterk, obstime=timek, weighti="constant", apertur=x,
      zmag=zmag, salgori=salgo, annulus=sannulus, dannulu=wannulus,
      calgori="none")

txdump(textfile=imname//'.mag.4',fields="ID,XCENTER,YCENTER,MAG,MERR,
        SHARPNESS", expr="ID>0", headers=yes,>imname//'.ape.4')

#-----
del header
del tmp.jd
imhead (imname, imlist=imname, longheader=yes, userfields=yes, > "header")
!awk '{if ($1=="JD") printf("%s \n",$3)}' header >> tmp.jd
#-----

print ("!./pasteall "//imname) | cl()
print ("!./diffphot "//imname//'.all') | cl()
mv ("diffout.dat", imname // ".diff")

    print(imname,>>simages)

}

}

else
{
    print ('image ',imname,' , psf list empty',>> errlog)
    print ('image ',imname,' PSF list is empty')
    # goto next image
}
# display subtracted image
if (im_disp)
{
    display(imname//'.sub.3',1)
}
# delete *.sub.# images
if (del_sub)
{
    imdelete(imname//'.sub.*',verify=no)
}
}

end

```

The following code is responsible for doing differential photometry on the output from the PSF and aperture photometry.

```

#include <string.h>
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <complex.h>

int main(int argc, char **argv)
{
    if (argc != 2)
    {
        printf("usage: %s filename \n", argv[0]);
    }

    //#####
    FILE *fp1;                                /*variables*/
    FILE *fp2;
    FILE *fp3;
    float b[4000][14];
    float mag_const, flux_const, flux[4000], delta_mag[4000], flux_err[4000],
          flux_const_err, delta_mag_err[4000];
    int a1;
    double jd;
    char s1[4000];
    int i,j,k,l,y,g,q, nlines;
    int id1=4, id2=5, id3=6, id4=8, id5=19, num[4000] ;
    //#####

    if((fp1=fopen(argv[1], "r")) == NULL) {
        printf("Cannot open file.\n", argv[1]);
        exit(1);
    }

    if((fp2=fopen("diffout.dat", "w+")) == NULL) {
        printf("Cannot open file.\n");
        exit(1);
    }

    if((fp3=fopen("tmp.jd", "r")) == NULL) {
        printf("Cannot open file.\n");
    }

```

```

        exit(1);
    }
//#####
                                /*read number of lines in .all file*/
char line[256], *tmpchar;
nlines = 0;
while (fgets(line, sizeof(line), fp1) != NULL)
    {
        tmpchar = &line[0];

        tmpchar++;
        fscanf (fp1, "%f\n", &a1);
        nlines = nlines + 1;

    }
//printf("%d \n", nlines);

//#####
rewind(fp1);                                /*read from .all file*/
rewind(fp2);

mag_const=0.0;
flux_const=0.0;
flux[1]=0.0;
delta_mag[1]=0.0;
flux_const_err = 0.0;
for(i=1;i<=nlines;i++)
{

    fscanf(fp1, "%d%f%f%f%f%f%f%f%f%f\n", &num[i], &b[i][2], &b[i][3],
    &b[i][4], &b[i][5], &b[i][6], &b[i][7], &b[i][8], &b[i][9], &b[i][10],
    &b[i][11], &b[i][12], &b[i][13], &b[i][14]);

    flux[i]=pow(10.0, -0.4*b[i][4]);
    flux_err[i]=0.4*flux[i]*logf(10)*b[i][5];

    if ((num[i]==id1)|| (num[i]==id2)|| (num[i]==id3)|| (num[i]==id4)|| (num[i]==id5))
    {

        flux_const += flux[i];
        flux_const_err += powf(flux_err[i],2.0);

    }
}
}

```

```

//b1 ID
//b2, b3 Coordinates
//b4, b5 Psf MAG + MERR
//b6 Sharpness
//b7, b8 Aperture1 MAG + MERR
//b9, b10 Aperture2 MAG +MERR
//b11, b12 Aperture3 MAG +MERR
//b13, b14 Aperture4 MAG +MERR

//printf("%5.5e %5.5e \n",flux_const, flux_const_err);

fscanf(fp3,"%lf \n", &jd);
//printf("%16.8lf \n",jd);

for(i=1;i<=nlines;i++)
{
    delta_mag[i]=(-2.5*log10f(flux[i]/flux_const));

    //fprintf(fp2, "%5.5e %5.5e \n",flux_err[i], flux_const_err);

    delta_mag_err[i] = sqrtf(powf(-2.5/log(10),2.0)*(powf(flux_err[i]/flux[i],2.0)
        +flux_const_err/powf(flux_const,2.0)));

    // $1=ID, $2=xcenter, $3=ycenter, $4=mag, $5=merr, $6=diff mag, $7=diff mag err

    fprintf(fp2, "%d %f %f %f %f %f %f %f %16.8lf \n", num[i], b[i][2], b[i][3],
        b[i][4], b[i][5], delta_mag[i], delta_mag_err[i], jd);

}

//#####

fclose(fp1);
fclose(fp2);
fclose(fp3);
return 0;
}

```

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